

23.5.2024 Properties of type families over pushouts in HoTT

Def A span on types  $A, B$  is a type  $S$  equipped with two maps  $A \xleftarrow{f} S \xrightarrow{g} B$

Def A span is a pair of types  $A, B$  and a span on them

Def A cocone on a span  $\mathcal{G}$  with vertex  $X$  is a pair of maps  $A \xrightarrow{i} X \xleftarrow{j} B$  and a homotopy witnessing that the square

$$\begin{array}{ccc} S & \xrightarrow{g} & B \\ f \downarrow & \Rightarrow & \downarrow j \\ A & \xrightarrow{i} & X \end{array} \quad \text{commutes} \quad \text{i.e. } H: (s:S) \rightarrow i(f(s)) = j(g(s))$$

Def For a cocone  $(i, j, H)$ , we define the cocone map

$$(X \rightarrow Y) \rightarrow \text{cocone } \mathcal{Y}$$

$$h \mapsto \begin{array}{ccccc} S & \xrightarrow{g} & B & \xrightarrow{j} & X \\ f \downarrow & h \cdot H \Rightarrow & \downarrow & \downarrow & \downarrow h \\ A & \xrightarrow{i} & X & \xrightarrow{h} & Y \end{array}$$

Def We say that a cocone  $(i, j, H)$  satisfies the universal property of pushouts if the cocone map is an equivalence for all  $Y$ 's

Def A dependent cocone over a cone  $(i, j, H)$  with vertex  $P: X \rightarrow \mathcal{U}$  is a triple  $(i', j', H')$  consisting of dependent maps  $i': (a:A) \rightarrow P(i a)$ ;  $j': (b:B) \rightarrow P(j b)$ ; and a "dependent homotopy"  $H': i' \circ f \sim_H j' \circ g$ , i.e.  $(s:S) \rightarrow \text{tr}_P(Hs) (i'fs) =_{P_{fs}} j'gs$

Def For a cocone  $(i, j, k)$ , we define the dependent cocone map

$$\begin{aligned} (x: X) \rightarrow P x &\rightarrow \text{dep-cocone } P \\ h &\mapsto (h \circ i, h \circ j, \lambda s \rightarrow \text{apd}_h(Hs)) \\ &\quad : \text{tr}_P(Hs) (hifs) = h jgs \end{aligned}$$

Def We say that a cocone satisfies the dependent universal property of pushouts if for all  $P$ , the dependent cocone map is an equivalence

Fact For any cocone  $c$ ,  $\Leftrightarrow^*$

- $c$  satisfies the universal property
- $c$  satisfies the dependent universal property

\* apparently not everyone is familiar with this symbol  
 - it means "the following are equivalent", and its shape suggests that each property implies the next, looping from the bottom to the top

Note In Homotopy Type Theory, there are often multiple different ways of describing "universality".

In a very handwavy way, they usually require a base sort of objects, maps, dependent/fibered objects and dependent/fibered maps, that we can equip with a functorial structure.

In "Homotopy Initial Algebras in Type Theory", Awodey, Gambino and Sojakova describe this phenomenon where the base sort are (dependent) types and (dependent) functions, and the structure is an algebra of a polynomial functor.

It was then extended by Sojakova in "Higher Inductive Types as Homotopy Initial Algebras" to cases where the structure is an algebra for a  $W$ -suspension, which is a generalization of  $W$ -types that allows path constructors (which is what we need for e.g. cocubes)

To set up, we can rearrange the arguments of the functorial action  $(X \rightarrow Y) \rightarrow \text{structure } X \rightarrow \text{structure } Y$ , so that for every structured object  $(X, s)$ , we get a map  $\text{ev-map}_Y : (X \rightarrow Y) \rightarrow \text{structure } Y$ .

There's also a dependent version for  $(X, s)$

$$\text{dep-ev-map} : (x : X) \rightarrow P_x \rightarrow \text{dep-structure}_{(X, s)} P$$

The general principle tells us that the following are equivalent:

- "initiality"
- $\text{ev-map}_Y$  is an equivalence // universal property
  - $\text{dep-ev-map}_P$  is an equivalence // dependent universal property
  - $\text{ev-map}_Y$  has a unique section // recursion + uniqueness
  - $\text{dep-ev-map}_P$  has a section // induction
- "induction"

We label the universal properties "initiality", since asking for e.g.  $\text{ev-map}_Y$  to be an equivalence for all  $Y$  means asking for its fibers to be contractible, which amounts to showing that for all structured objects  $(Y, s')$ , the type  $\Sigma(h: X \rightarrow Y). \text{ev-map } h = s'$  is contractible, and the mental image of  $(\text{ev-map } h)$  should be evaluating  $h$  at the structure  $s$  on  $X$ , so we are asking for the type of structure preserving maps from  $(X, s)$  to any  $(Y, s')$  to be contractible. That's a HoTT way of saying that  $(X, s)$  is initial.

For a concrete example, we may consider the case of pointed types. The structure on a type  $A$  is an element  $a_0$  of  $A$ , and the structure on a family  $P: A \rightarrow \mathcal{U}$  over  $(A, a_0)$  is an element  $p_0$  of  $P(a_0)$ .

The evaluation maps turn out to be

$$\begin{array}{ll} \text{ev-map}_Y : (A \rightarrow Y) \rightarrow Y & \text{dep-ev-map}_P : ((a:A) \rightarrow P a) \rightarrow P a_0 \\ h \mapsto h a_0 & h \mapsto h a_0, \end{array}$$

so a section of  $\text{ev-map}$  is a mapping from  $(Y, y_0)$  to the type  $\Sigma(h: A \rightarrow Y). h a_0 = y_0$  of point-preserving maps, and so on.

At the end of the talk, we will see the induction principle of descent data for identity systems, where the sort of objects is descent data, and the structure is a point. We could instead work with an analogous universal property or recursion & uniqueness (as done by Kraus and von Raumer in "Path Spaces of Higher Inductive Types"). The choice of induction principle was made purely speculatively, guessing which property would be easier to formalize.

## Descent

Motivation We want a nice description of what type families over pushouts "look like". We can already see that the type  $(X \rightarrow U)$  is equivalent to the type of cocones with vertex  $U$ . That type includes an identification in  $U$ , so we can "clean" it up using univalence

Convention In the rest of the talk, let us assume a span  $\mathcal{S}$

$$\begin{array}{ccc} & S & \xrightarrow{g} B \\ f \downarrow & & \\ & A & \end{array}, \quad \text{a cocone } c$$

$$\begin{array}{ccccc} & S & \xrightarrow{g} & B & \\ f \downarrow & & \searrow H & \searrow j & \\ & A & \xrightarrow{i} & X & \end{array} \quad \text{and}$$

$\alpha$  witness UP of  $c$  satisfying the universal property of pushouts

Def Descent data (for pushouts) consists of type families  $P_A: A \rightarrow U$ ,  $P_B: B \rightarrow U$ , and a family of equivalences  $P_s: (s: S) \rightarrow P_A(fs) \simeq P_B(gs)$

Construction A type family  $P: X \rightarrow U$  induces the descent data

descent-data-family  $P := (P \circ i, P \circ j, \lambda s \rightarrow \text{tr}_P(Hs))$

Prop There is a commuting triangle

$$\begin{array}{ccc} (X \rightarrow U) & \xrightarrow{\text{cocone-map}} & \text{cocone } U \\ \text{dd-fam} \searrow & \simeq & \swarrow \text{tot (tot (equiv-eg))} \\ & \text{descent-data} & \end{array}$$

Proof We need to check that  $(P \circ i, P \circ j, \lambda s \rightarrow \text{tr}_p(Hs)) = (P \circ i, P \circ j, \lambda s \rightarrow \text{equiv-eq}(\text{ap}_p(Hs)))$

Since the first two components are identical, it suffices to show  $(s:S) \rightarrow \text{tr}_p(Hs) = \text{equiv-eq}(\text{ap}_p(Hs))$ , which is a general principle:

Lemma For all  $Y:U, p:Y \rightarrow U, x, y:Y, p: x = y$ , we have  $\text{tr}_p p = \text{equiv-eq}(\text{ap}_p p)$

Proof By path induction, it suffices to consider the case  $y = x, p = \text{id}$ . Then the statement reduces to  $\text{id} = \text{id}$ , which holds by reflexivity

Corollary The map  $(X \rightarrow W) \rightarrow \text{descent-data}$  is an equivalence, by the 3-for-2 property of equivalences

Def Given descent data  $(P_A, P_B, P_S), (Q_A, Q_B, Q_S)$ , the type of morphisms between them is given by the type

$$(P_A, P_B, P_S) \rightarrow (Q_A, Q_B, Q_S) := \sum (h_A : (a:A) \rightarrow P_A a \rightarrow Q_A a), \sum (h_B : (b:B) \rightarrow P_B b \rightarrow Q_B b), h_S : (s:S) \rightarrow \begin{array}{ccc} P_A(fs) & \xrightarrow{h_A(fs)} & Q_A(fs) \\ P_S s \downarrow & \nearrow & \downarrow Q_S s \\ P_B(gs) & \xrightarrow{h_B(gs)} & Q_B(gs) \end{array}$$

Def Similarly, equivalences of descent data are like morphisms, except  $h_A, h_B$  are fiberwise equivalences

Prop Equivalences of descent data characterize their identity type, i.e. the canonical map

$$\text{equiv-eg-dd} : ((P_A, P_B, P_S) = (Q_A, Q_B, Q_S)) \rightarrow (P_A, P_B, P_S) \simeq (Q_A, Q_B, Q_S)$$

$$\text{refl} \mapsto (\text{id}, \text{id}, \text{refl-htpy})$$

is an equivalence

Proof Mechanical by the structure identity principle

Note It will be useful to talk about families equipped with descent data, as a way to parameterize constructions by user-provided equivalences

Def A family equipped with descent data, denoted  $P \simeq (P_A, P_B, P_S)$ , is a triple consisting of a type family  $P: X \rightarrow \mathcal{U}$ , descent data  $(P_A, P_B, P_S)$ , and an equivalence of descent data descent-data-family  $P \simeq (P_A, P_B, P_S)$

Note Unfoldly, we have two fiberwise equivalences

$$e_A : (a:A) \rightarrow P(a) \simeq P_A a$$

$$e_B : (b:B) \rightarrow P(b) \simeq P_B b$$

and a square

$$\begin{array}{ccc} e_S : (s:S) \rightarrow & & \\ P(is) & \xrightarrow{e_A(is)} & P_A(is) \\ \text{tr}_P(Hs) \downarrow & \Rightarrow & \downarrow P_S s \\ P(jgs) & \xrightarrow{e_B(jgs)} & P_B(jgs) \end{array}$$

Corollary For every descent data  $(P_A, P_B, P_S)$ , there is a unique family  $P: X \rightarrow U$  s.t.  $P \approx (P_A, P_B, P_S)$

Proof The type  $\Sigma (P: X \rightarrow U). P \approx (P_A, P_B, P_S)$  is equivalent to  $\Sigma (P: X \rightarrow U). \text{dd-fam } P = (P_A, P_B, P_S)$ , which is the type  $\text{fib}_{\text{dd-fam}} (P_A, P_B, P_S)$ . Since dd-fam is an equivalence, its fibers are contractible

Prop Given two families with descent data  $P \approx (P_A, P_B, P_S)$ ,  $Q \approx (Q_A, Q_B, Q_S)$ , the descent data corresponding to the family  $\lambda x \rightarrow P_x \rightarrow Q_x$  is

$$\begin{aligned} & (\lambda a \rightarrow P_A a \rightarrow Q_A a, \\ & \lambda b \rightarrow P_B b \rightarrow Q_B b, \\ & \lambda s \rightarrow \lambda h \rightarrow e_S^{Q_S} s \circ h \circ e_{SS}^{P_S^{-1}} ) \\ & : (P_A(b) \rightarrow Q_A(b)) \approx (P_B(g_S) \rightarrow Q_B(g_S)) \end{aligned}$$

// note that pre- and post-composition by equivalences are equivalences

Proof Uses the characterization of transport in families of function types  $\text{tr}_{(x \rightarrow P_x \rightarrow Q_x)} P f = \text{tr}_Q P \circ f \circ \text{tr}_P (P^{-1})$

Construction Given families with descent data  $P \approx (P_A, P_B, P_S)$  and  $Q \approx (Q_A, Q_B, Q_S)$ , there is a map

$$\begin{aligned} ((x: X) \rightarrow P_x \rightarrow Q_x) & \rightarrow (P_A, P_B, P_S) \rightarrow (Q_A, Q_B, Q_S) \\ h & \mapsto (\lambda a \rightarrow e_A^{Q_A} a \circ h(ia) \circ e_A^{P_A^{-1}}, \\ & \lambda b \rightarrow e_B^{Q_B} b \circ h(jb) \circ e_B^{P_B^{-1}}, \\ & \lambda s \rightarrow K(\text{apd}_h(Hs))) \end{aligned}$$

where  $K$  is the composed equivalence:



$$\begin{aligned}
 (\text{tr}_{Q \rightarrow P \rightarrow R} (H_S) (h(i_f_S)) = h(j_g_S)) &\simeq (\text{tr}_Q (H_S) \circ h(i_f_S) \circ \text{tr}_P (H_S)^{-1} = h(j_g_S)) \\
 &\simeq (\text{tr}_Q (H_S) \circ h(i_f_S) \sim h(j_g_S) \circ \text{tr}_P (H_S)) \simeq (e_B^R(g_S) \circ h(j_g_S) \circ e_B^P(g_S)^{-1} \circ P_S S \\
 &\quad \sim Q_S S \circ e_A^R(f_S) \circ h(i_f_S) \circ e_A^P(f_S)^{-1})
 \end{aligned}$$

where the last equivalence is given by pasting squares

$$\begin{array}{ccccc}
 P(i_f_S) & \xrightarrow{h(i_f_S)} & Q(i_f_S) & & P_A f_S \xrightarrow{e_A^P(f_S)^{-1}} P(i_f_S) \xrightarrow{h(i_f_S)} Q(i_f_S) \xrightarrow{e_A^R(f_S)} Q_A f_S \\
 \text{tr}_P(H_S) \downarrow & & \downarrow \text{tr}_Q(H_S) & \simeq & P_S S \downarrow & \downarrow \text{tr}_P(H_S) & \downarrow & \downarrow Q_S S \\
 P(j_g_S) & \xrightarrow{h(j_g_S)} & Q(j_g_S) & & P_B g_S \xrightarrow{e_B^P(g_S)^{-1}} P(j_g_S) \xrightarrow{h(j_g_S)} Q(j_g_S) \xrightarrow{e_B^R(g_S)} Q_B g_S
 \end{array}$$

Prop The above map is an equivalence

Corollary Given a morphism of descent data  $(h_A, h_B, h_S): (P_A, P_B, P_S) \rightarrow (Q_A, Q_B, Q_S)$ , the type of maps  $h: (x: X) \rightarrow P_x \rightarrow Q_x$  such that the following diagrams commute, is contractible

$$\begin{array}{ccc}
 P(i_a) & \xrightarrow{h(i_a)} & Q(i_a) \\
 e_A^P \downarrow & & \downarrow e_A^Q \\
 P_A a & \xrightarrow{h_A a} & Q_A a
 \end{array}
 \quad
 \begin{array}{ccc}
 P(j_b) & \xrightarrow{h(j_b)} & Q(j_b) \\
 e_B^P \downarrow & & \downarrow e_B^Q \\
 P_B b & \xrightarrow{h_B b} & Q_B b
 \end{array}$$

$$\begin{array}{ccccc}
 & & P(i_f_S) & & \\
 & \swarrow \text{tr}_P(H_S) & \downarrow e_A^P(f_S) & \searrow h(i_f_S) & \\
 P(j_g_S) & & P_A(f_S) & & Q(i_f_S) \\
 e_B^P(g_S) \downarrow & \swarrow h(j_g_S) & \downarrow h_A(f_S) & \searrow \text{tr}_Q(H_S) & \downarrow e_A^R(f_S) \\
 P_B(g_S) & & Q(j_g_S) & & Q_A(f_S) \\
 h_B(g_S) \downarrow & & \downarrow e_B^R(g_S) & & \downarrow Q_S S \\
 & & Q_B(g_S) & & 
 \end{array}$$

$\text{apd}_h(H_S): \text{tr}_Q(H_S) \circ h(i_f_S) \circ \text{tr}_P(H_S)^{-1} = h(j_g_S)$   
 $\leadsto \text{tr}_Q(H_S) \circ h(i_f_S) \sim h(j_g_S) \circ \text{tr}_P(H_S)$  is the top face

Prop Similarly a family of equivalences  $(x:X) \rightarrow P_x \simeq Q_x$  is given by an equivalence  $(P_A, P_B, P_S) \simeq (Q_A, Q_B, Q_S)$

Note These correspondences can be abstracted further by defining sections of descent data, and observing that sections of  $P$  correspond to sections of  $(P_A, P_B, P_S)$

Def A section of descent data  $(P_A, P_B, P_S)$  is a triple  
 $(t_A: (a:A) \rightarrow P_A a,$   
 $t_B: (b:B) \rightarrow P_B b,$   
 $t_S: (s:S) \rightarrow P_S s \text{ (} t_A(fs) = t_B(gs) \text{)})$

Prop Given  $P \simeq (P_A, P_B, P_S)$ , sections  $t: (x:X) \rightarrow P_x$  of  $P$  are given by sections of  $(P_A, P_B, P_S)$ , and we have the computation rules

$$\begin{array}{ccc} (a:A) & \xrightarrow{t_A} & P_A a \\ i \downarrow & & \uparrow e_A a \\ (ia:X) & \xrightarrow{t} & P(ia) \end{array} \qquad \begin{array}{ccc} (b:B) & \xrightarrow{t_B} & P_B b \\ j \downarrow & & \uparrow e_B b \\ (jb:X) & \xrightarrow{t} & P(jb) \end{array}$$

I'm sorry I don't know how to draw this better

$$\begin{array}{ccc} & & (s:S) \xrightarrow{t_S} P_S s \text{ (} t_A(fs) = t_B(gs) \text{)} \\ & \swarrow H & \uparrow \text{above computations} \\ (Hs: ifs = jgs) & & P_S s (e_A(fs)(t ifs)) = e_B(gs)(t jgs) \\ \text{apd}_t \downarrow & & \uparrow e_S^{-1} \cdot - \\ \text{tr}_P(Hs)(t ifs) = t jgs & & \\ \text{ap}_{e_B(gs)} \downarrow & & \\ e_B(gs)(\text{tr}_P(Hs)(t ifs)) = e_B(gs)(t jgs) & & \end{array}$$

Proof (sketch) The map factorizes as

$$\begin{array}{ccc}
 (\omega: X) \rightarrow P_x & \xrightarrow{\simeq} & \text{top-convex } c P \\
 \downarrow & & \downarrow \simeq \\
 & & \text{section } (P_A, P_B, P_S)
 \end{array}$$

Where the top map is an equivalence by UP, and the right map is an equivalence constructed using functoriality of  $\Sigma$

Prop Given a point  $a_0: A$ , the family  $\text{Id}_X (ia_0): X \rightarrow U$   
 $x \mapsto ia_0 = x$   
 is characterized by the descent data

$$\begin{array}{l}
 (I_A: A \rightarrow U \\
 a \mapsto ia_0 =_x ia \\
 I_B: B \rightarrow U \\
 b \mapsto ia_0 =_x jb \\
 I_S: (s: S) \rightarrow I_A(fs) \simeq I_B(gs) \\
 s \mapsto - \cdot Hs \\
 : (ia_0 = ifs) \simeq (ia_0 = jgs) )
 \end{array}$$

Proof  $e_A: (a:A) \rightarrow (ia_0 = ia) \simeq (ia_0 = ia) \quad \checkmark \quad \text{id}$

$e_B: (b:B) \rightarrow (ia_0 = jb) \simeq (ia_0 = jb) \quad \checkmark \quad \text{id}$

$e_S: (s:S) \rightarrow (ia_0 = ifs) \xrightarrow{\text{id}} (ia_0 = ifs) \quad \checkmark$

$$\begin{array}{ccc}
 \text{tr}_{\text{Id}_X ia_0} (Hs) \downarrow & \rightsquigarrow & \downarrow - \cdot Hs \\
 ia_0 = jgs & \xrightarrow{\text{id}} & (ia_0 = jgs)
 \end{array}$$

general lemma  
 characterizing  
 transport in  
 based identity types

Recap We built a dictionary for translating between families over pushouts and descent data

Type families

Descent data

obj  $P: X \rightarrow U$

$(P_A, P_B, P_S)$

hom  $(x: X) \rightarrow P_x \rightarrow Q_x$

$(P_A, P_B, P_S) \rightarrow (Q_A, Q_B, Q_S)$

equiv  $(x: X) \rightarrow P_x \simeq Q_x$

$(P_A, P_B, P_S) \rightarrow (Q_A, Q_B, Q_S)$

section  $(x: X) \rightarrow P_x$

section  $(P_A, P_B, P_S)$

based identity

system  $\lambda x \rightarrow x_0 =_X x$

$(I_A, I_B, I_S)$

todo induction principle of based identity systems, allowing for alternative constructions

" $P: X \rightarrow U$ ,  $x_0: X$ ,  $p_0: P_{x_0}$   
is an identity system if  
for all  $Q: (x: X) \rightarrow P_x \rightarrow U$   
the evaluation map

ev-refl<sub>Q</sub>:  $((x: X) \rightarrow (p: P_x) \rightarrow Q_x p)$   
 $\rightarrow Q_{x_0} p_0$

$h \mapsto h_{x_0} p_0$

has a section"

then there is a unique equivalence  
 $(x: X) \rightarrow (x_0 =_X x) \simeq P_x$  taking refl<sub>x</sub>  
to  $p_0$ .

We can start:

" $(P_A, P_B, P_S)$ ,  $a_0: A_0$ ,  $p_0: P_A a_0$   
is an identity system  
if for all ???"

$\rightarrow$  we don't have a  
description of families  
of shape  $(x: X) \rightarrow P_x \rightarrow U$

then there is a unique equivalence  
 $(F_A, I_B, I_S) \simeq (P_A, P_B, P_S)$  taking  
refl<sub>a\_0</sub> to  $p_0$ .

BUT! We can uncurry

$P: X \rightarrow U, x_0: X, p_0: P x_0$   
 is an identity system if  
 for all  $Q: \Sigma X P \rightarrow U$ ,  
 the evaluation map  
 $ev\text{-refl}_Q: ((u: \Sigma X P) \rightarrow Q u)$   
 $\rightarrow Q(x_0, p_0)$   
 $h \mapsto h(x_0, p_0)$   
 has a section

$(P_A, P_B, P_S), a_0: A, p_0: P_A a_0$   
 is an identity system if  
 for all  $(Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S})$   
 the evaluation map  
 $ev\text{-refl}' : \text{section}(Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S})$   
 $\rightarrow Q_{\Sigma A}(a_0, p_0)$   
 $(t_A, t_B, t_S) \mapsto t_A(a_0, p_0)$   
 has a section

IOW, every  $q_0: Q(x_0, p_0)$   
 induces a section  $h: (u: \Sigma X P) \rightarrow Q u$   
 such that  $h(x_0, p_0) = q_0$

IOW, every  $q_0: Q_{\Sigma A}(a_0, p_0)$   
 induces a section  $t: \text{section}(Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S})$   
 such that  $t_A(a_0, p_0) = q_0$

HOWEVER! Now we are talking about the cocone

$$\begin{array}{ccc}
 \Sigma S (P_A \circ f) & \xrightarrow{\text{tot}_g^B} & \Sigma B P_B \\
 \text{tot}_f \text{id} \downarrow & \text{tot}_H (\text{flip } e_S)^{-1} & \downarrow \text{tot}_j e_B^{-1} \\
 \Sigma A P_A & \xrightarrow{\text{tot}_i e_A^{-1}} & \Sigma X P
 \end{array}$$

where  $\text{flip}(e_S) : (s: S) \rightarrow P_A(fs) \xrightarrow{e_A(B)^{-1}} P(is)$

$$\begin{array}{ccc}
 P_S \downarrow & & \downarrow \text{tr}_P(Hs) \\
 P_B(gs) & \xrightarrow{e_B(S)^{-1}} & P(jgs)
 \end{array}$$

and we don't know anything about families over it,  
 since we only know that  $c$  is a pushout, not  
 that this  $\Sigma c$  is a pushout. Is it?

## Flattening

Lemma (flattening) It is!

Note When (properly) stating and proving the flattening lemma, it is convenient to consider families with descent data where the equivalence goes the other way, i.e.  $(P_A, P_B, P_S) \approx P$  instead of  $P \approx (P_A, P_B, P_S)$ .

Lemma (flattening) Given  $(P_A, P_B, P_S) \approx P$ , the cocone

$$\begin{array}{ccc}
 \Sigma S (P \circ f) & \xrightarrow{\text{tot}_f^+ P_S} & \Sigma B P_B \\
 \text{tot}_f^+ \text{id} \downarrow & \text{tot}_H^+ e_S^{-1} \nearrow & \downarrow \text{tot}_j^+ e_B \\
 \Sigma A P_A & \xrightarrow{\text{tot}_i^+ e_A} & \Sigma X P
 \end{array}$$

satisfies the universal property of pushouts

Proof The proof consists of two steps:

1) We show that

$$\begin{array}{ccc}
 \Sigma S (P \circ i \circ f) & \xrightarrow{\text{tot}_f^+ (\text{tr}_P(H_S))} & \Sigma B (P \circ j) \\
 \text{tot}_f^+ \text{id} \downarrow & \text{tot}_H^+ \text{refl} \nearrow & \downarrow \text{tot}_j^+ \text{id} \\
 \Sigma A (P \circ i) & \xrightarrow{\text{tot}_i^+ \text{id}} & \Sigma X P
 \end{array}$$

is a pushout

2) We observe that the two squares of total spaces are "equivalent" in a way that preserves the universal property

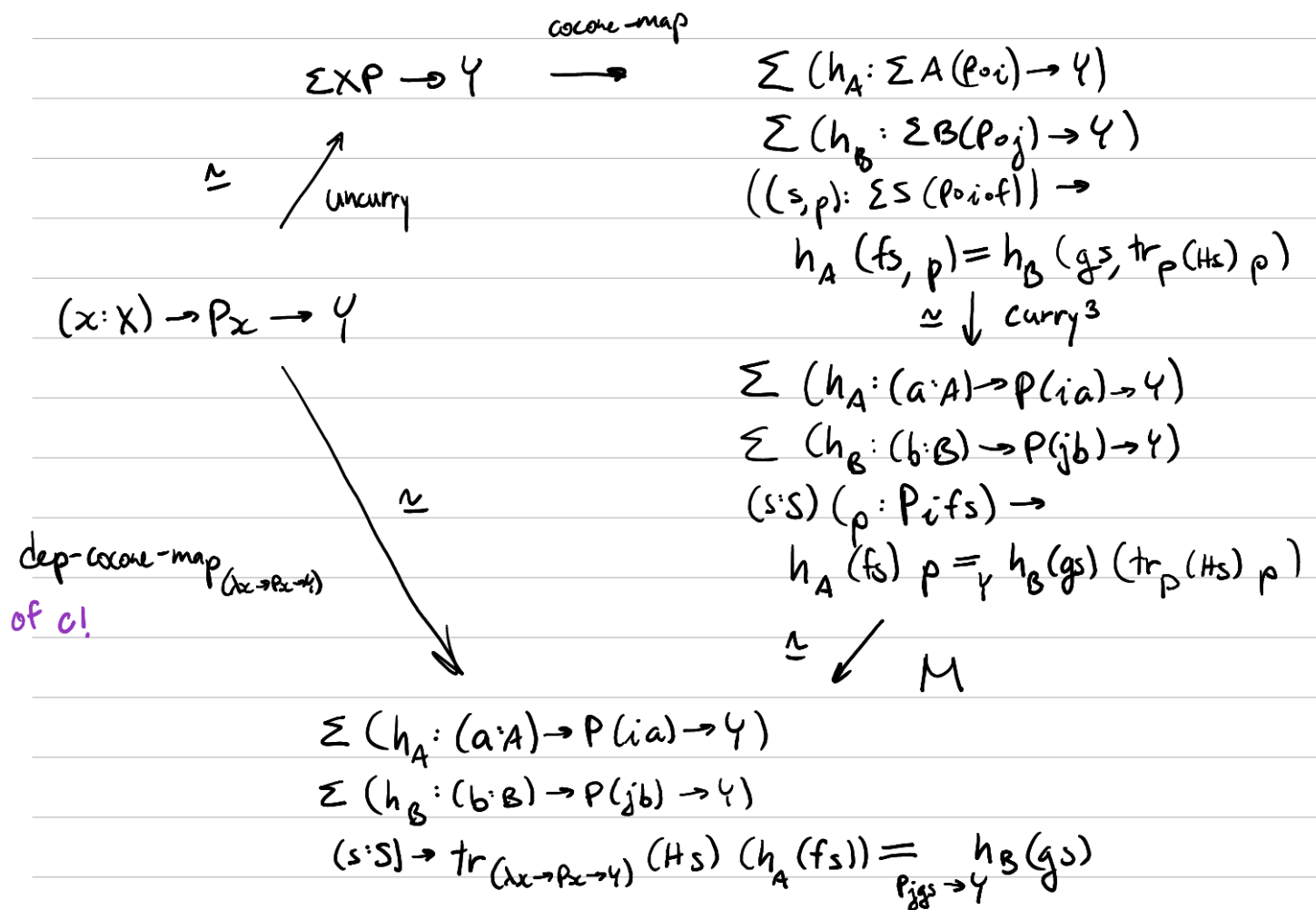
1) We need to show that

$$\text{cocore-map}_Y: (\Sigma X P \rightarrow Y) \rightarrow \text{cocore } Y$$

$$h \mapsto (h \circ \text{tot}_i \text{ id}, h \circ \text{tot}_j \text{ id}, h \circ \text{tot}_H \text{ refl})$$

is an equivalence.

We can form a commuting pentagon



where the equivalence  $M: ((p: P i f s) \rightarrow h_A(fs) p = h_B(gs) (tr_p(Hs) p)) \cong (tr_{(X \rightarrow P \rightarrow Y)}(Hs) (h_A(fs)) =_{P(j \rightarrow Y)} h_B(gs))$

is constructed in full generality as

For all  $i, j: S \rightarrow X, H: i \sim j, P: X \rightarrow U, Y: U,$   
 $k: (s: S) \rightarrow P(i s) \rightarrow Y, l: (s: S) \rightarrow P(j s) \rightarrow Y, s: S,$   
 $((p: P(i s)) \rightarrow k s p =_Y l s (tr_p(Hs) p))$   
 $\cong tr_{(X \rightarrow P \rightarrow Y)}(Hs) (k s) =_{P(j \rightarrow Y)} l s$

using homotopy induction, we may assume that  $j = i$ ,  
 $H = \text{refl-htpy}$ . Then it suffices to show that  
 $((p: P(i)) \rightarrow k s p = l s p) \simeq (k s = l s)$ ,  
 which holds by function extensionality.

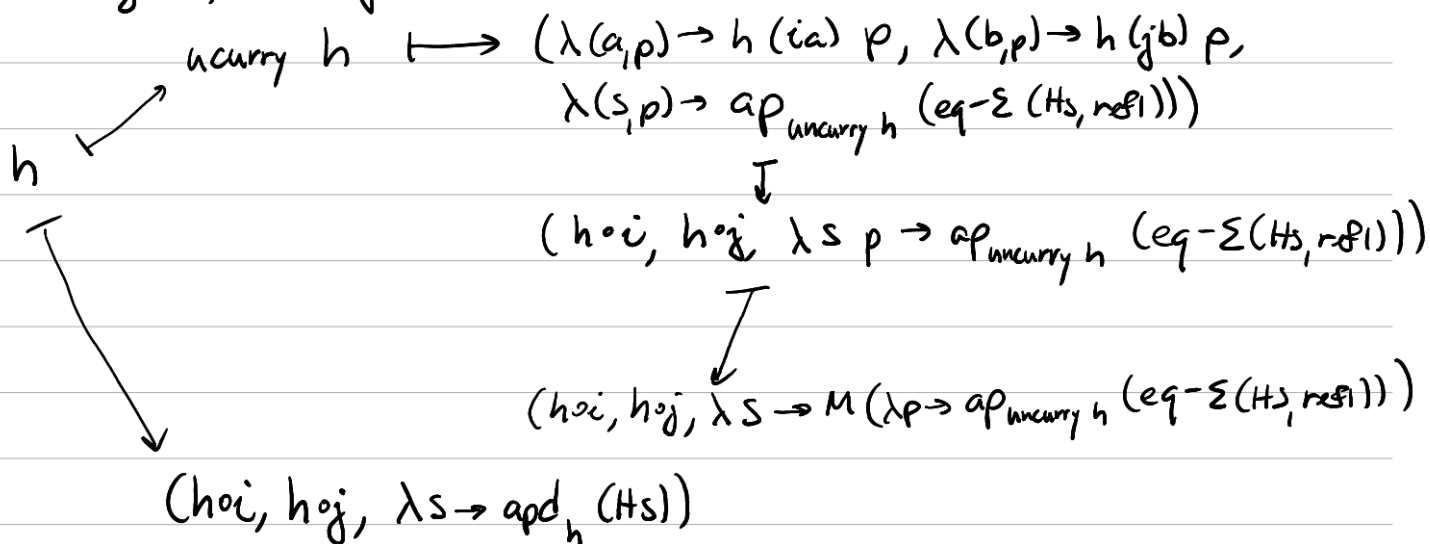
Also by homotopy induction, we show the computation  
 rule: For all  $h: (x: X) \rightarrow P x \rightarrow Y$ , we have

$$M (h \circ i) (h \circ j) (\lambda p \rightarrow \text{ap}_{\text{uncurry } h} (\text{eq-}\Sigma(Hs, \text{refl}))) = \text{apd}_h (Hs)$$

// sanity check:  $\text{uncurry } h : \Sigma X P \rightarrow Y$ ,  $\text{eq-}\Sigma(Hs, \text{refl}) : (i s, p) =_{\Sigma X P} (j s, \text{tr}_P(Hs) p)$   
 $\rightarrow \text{ap} \dots : h (i s) p = h (j s) (\text{tr}_P(Hs) p)$   
 $\rightarrow M \dots : \text{tr} (Hs) (h (i s)) = h (j s)$  ✓  
 $\text{apd}_h (Hs) : \text{tr} (Hs) (h (i s)) = h (j s)$

the computation itself is omitted

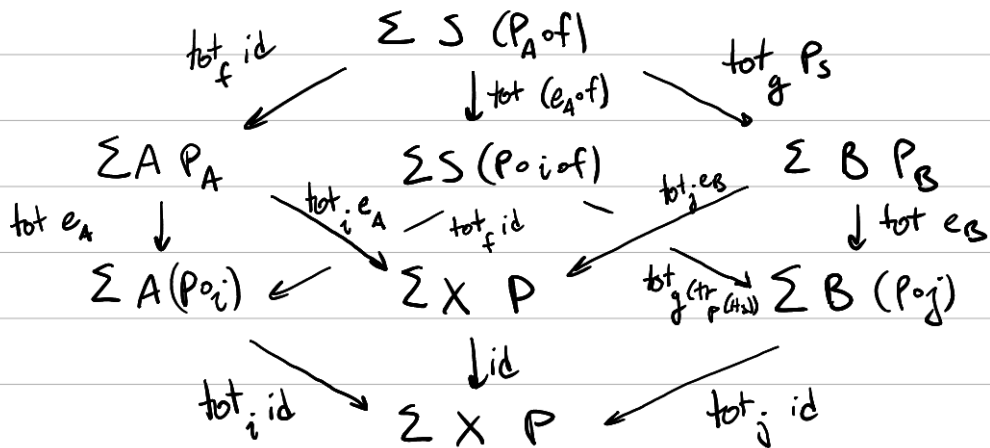
Chasing an element  $h: (x: X) \rightarrow P x \rightarrow Y$  along the  
 diagram, we get



and the endpoints are equal by the above computation



2) There is a commuting cube (commutativity omitted, but not terribly difficult)



where the vertical maps are equivalences. This data is an equivalence of commuting squares, and since the bottom is a pushout, we get that the top is a pushout

Prop The descent data  $(I_A, I_B, I_S)$  with  $\text{refl}_{i_{a_0}}: I_A a_0$  satisfies the induction principle of identity systems

Proof Assume descent data  $(Q_{EA}, Q_{EB}, Q_{ES})$ . Then there exists a unique family  $Q: (\Sigma(x: X). i_{a_0} = x) \rightarrow U$  such that  $Q \vDash (Q_{EA}, Q_{EB}, Q_{ES})$ . There is a commuting square

$$\begin{array}{ccc}
 (u: \Sigma(x: X). i_{a_0} = x) \rightarrow Q u & \xrightarrow{\quad} & \text{section } (Q_{EA}, Q_{EB}, Q_{ES}) \\
 \text{ev-refl} \downarrow & & \downarrow \text{ev-refl}' \\
 Q(i_{a_0}, \text{refl}_{i_{a_0}}) & \xrightarrow{e_A^Q(a_0, \text{refl}_{i_{a_0}})} & Q_{EA}(a_0, \text{refl}_{i_{a_0}})
 \end{array}$$

$$\begin{array}{ccc}
 t & \xrightarrow{\quad} & (t_A, t_B, t_S) \\
 \downarrow & & \downarrow \\
 & & t_A(a_0, \text{refl}_{i_{a_0}}) \\
 & & = \\
 t(i_{a_0}, \text{refl}_{i_{a_0}}) & \xrightarrow{\quad} & e_A^Q(t(i_{a_0}, \text{refl}_{i_{a_0}}))
 \end{array}$$

commutes by computation of  $t_A$

Since  $\text{ev-refl}$ ,  $e_A^Q(a_0, \text{refl}_{i_{a_0}})$ , and the top map are equivalences, then  $\text{ev-refl}'$  is also an equivalence, in particular it has a section

Prop For any descent data  $(P_A, P_B, P_S)$  and  $p_0: P_A a_0$  satisfying the induction principle of identity systems, there is an equivalence  $(I_A, I_B, I_S) \simeq (P_A, P_B, P_S)$  sending  $\text{refl}_{ia_0}$  to  $p_0$ .

Proof There is a unique family  $P: X \rightarrow U$  such that  $P \simeq (P_A, P_B, P_S)$ . To give an equivalence  $(I_A, I_B, I_S) \simeq (P_A, P_B, P_S)$  sending  $\text{refl}_{ia_0}$  to  $p_0$  is to give an equivalence  $(x: X) \rightarrow (ia_0 = x) \simeq P x$  sending  $\text{refl}_{ia_0}$  to  $e_{A a_0}^{-1}(p_0): P(ia_0)$ .

We can define such a map by path induction.

To show that it is an equivalence, by the fundamental theorem of identity types it suffices to show that  $\Sigma X P$  is contractible.

It is contractible exactly when it satisfies

singleton induction: For all  $Q: \Sigma X P \rightarrow U$ ,

the evaluation map  $\text{ev-refl}: ((u: \Sigma X P) \rightarrow Q u) \rightarrow Q(ia_0, e_{A a_0}^{-1}(p_0))$   
 $h \mapsto h(ia_0, e_{A a_0}^{-1}(p_0))$

has a section. It fits into a commuting square

$$\begin{array}{ccc}
 \text{section } (Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S}) & \xrightarrow{\quad} & (u: \Sigma X P) \rightarrow Q u \\
 \text{ev-refl}' \downarrow & & \downarrow \text{ev-refl} \\
 Q_{\Sigma A}(a_0, p_0) & \xrightarrow{e_{A a_0}^{-1}} & Q(ia_0, e_{A a_0}^{-1}(p_0))
 \end{array}$$

where  $(Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S})$  is the unique descent data such that  $Q \simeq (Q_{\Sigma A}, Q_{\Sigma B}, Q_{\Sigma S})$ . The square commutes by mirroring the computation square of  $t_A$ . Both  $e_{A a_0}^{-1}$  and  $\text{ev-refl}'$  have a section, so  $\text{ev-refl}$  has one